

Al in Aircraft Maintenance

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DEAGLE

Digital, sustainable, global.

Deagle is an Innovative Start-up founded by a team of managers and engineers, combining their experience in high technology fields





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Digital, sustainable, global.





Engineering Certification & Prototype Manufacturing & Integration



INDUSTRIAL INNOVATION

Research and development

Pre-industrialization

Automation

Artificial Intelligence

Product support



RENEWABLE ENERGY

Eco Friendly Innovative Flexible solution



ARTIFICIAL INTELLIGENCE PLATFORM

Deagle is able to merge the high potentiality tools based on Artificial Intelligence in many fields of application varying from **medical sector products to industrial applications**, whose technical background is firmly owned by Deagle team.

Deagle uses cutting edge **machine learning** and **artificial intelligence** to rapidly and repeatedly deliver customer insights and advantages from his own data, to have the predictive power needed to drive change and innovation. developing customized platform of data analytics, based on his property AI engines,





ARTIFICIAL INTELLIGENCE: PAST EXPERIENCE IN STORE ANALYTICS

IN-STORE ANALYTICS



- Creating the Custamer Funnel in the store, to evaluate ROI, from the Showcose to the Checkaut
- Understanding the customer with a full range of emotion analysis: lear, surprise, happiness, sadness
- Gender and aga, ethnicity
- Defining visitor segments and distribution by age, awell ima, frequency, best and warst days, and more.
- Creating Heat Maps.





HOLMeS: Medical Disease Prediction

-support medical decision -integrate the platform with nano-device -collaborate and interact with health organizations -active health monitoring





HORUS project – Bando 2 Meditech

The HORUS project aims to develop a technological solution capable of identifying and validating new aircraft fuselage **inspection** procedures.

The solution is based on image processing technology, and the idea behind the project is to use **automatic** devices for **visual inspections** in a process that drastically reduces the time to complete such tasks.







UNIONE EUROPEA Fondo europeo di sviluppo regionale



Leader – AI, Engineering, Automation



Industrial Partner– Aircraft Maintenance



Partner – Experimental measurement, Engineering





HORUS project - Objectives







| Before HORUS | After HORUS | | |
|---|--|--|--|
| standard approach for quality/maintenance | automatic quality/maintenance evaluation | | |
| management | system | | |
| visual inspection of the aircraft by expert | automatic aircraft verification | | |
| technicians | | | |
| general not specific requirements for image | ability to define image processing | | |
| processing | requirements to improve industrial | | |
| processing | production | | |
| very preliminary application of image | HW identification and SW development for | | |
| processing to resolve manufacturing | image processing systems aimed at | | |
| nonconformities | production assistance | | |



HORUS project - Requirements

- Definition of requirements for each type of defect
 - ✓ absence of rivet
 - ✓ scratches
 - ✓ writings/decals missing or damaged
 - ✓ dents





• Selection of typical components to carry out inspections and calibration of the system









HORUS project – Experimental environment

Image acquisition phase of defects making use of the collaboration of **Meditech (CESMA)**, whose laboratory hosts a full-scale fuselage section of an A320, as well as an almost intact fuselage of an AG P2006 aircraft, on which it was possible to reproduce typical defects









HORUS project – Acquisition campaign

• The acquisition equipment for this first phase is a Nikon 3200 **digital reflex camera**, Pixel 24M, 23.2x15.4mm2 CMOS sensor, which gives the opportunity to acquire images with different technical characteristics (focal length, aperture, artificial light from flash or not, shutter speed,...) to identify the limits and ideal operating range for the recognition software.

| NOME FOTO | SOGGETTO | DISTANZA (CAMBRA-TARGET) | LUNGHEZZA FOCALE | ILLUMINAZIONE | 1000 | |
|---------------|----------------------------------|-----------------------------|---------------------|---------------|-----------------------|----------|
| foto_0001.IPG | Pannello rivettato, futoliera | 30 cm | 18 mm | NO finik | Server and Server and | |
| nto_0002.0PG | Pannello rivettato, functiona | 30 cm | 15 mm | flash | Rive | t |
| foto_0003.IPG | Pannello rivettato, fundiara | 30 cm | 18 mm | Luce naturale | | |
| fotu_0004.IPG | Pannello rivettato, fasoliera | 80 cm | 55 mm | NO firsh | | |
| foto_0005.IPG | Pannello rivettato, facolicea | 80 cm | 55 mm | flach | | |
| ioto_0006.IPG | Paunello rivettata. fusoliera | 80 cm | 55 mm | Luce naturale | | |
| foto_0007.3PG | Pannello rivettatu, fanoliera | 30 cm | 18 mm | NO flash | - | |
| foto_0008.JPG | Panoello rivettato, fasoliera | 80 cm | 18 mm | fiash | Missir | ng Rivet |
| foto_0009.3PG | Pannello rivettato, fasoliera | 60 cm | 18 mm | Luce asturale | | 0 |
| | 44 | | | | | |

• In the next phase, the acquisition system will be degraded to make it suitable for **commercial application** and to be easily transported by an automatic system in the aircraft fuselage, therefore the actual software training campaign will be repeated and in-depth based on images from a smartphone or Go-Pro like instrument.



HORUS project – Typical defects



Scratch

Dents



ADF SENSE ANTENNA (DO NOT USE CONDUCTIVE PAINT) Labels





HORUS project – Algorithms development

Architecture: LeNet model, by mixing convolutional layers with pooling up to fully connected layer linked to neurons for class prediction.

Training: Model has been trained with Grid Search method, by using 100 epochs to find the optimal iperparameters and monitoring the accuracy of classification, the loss function and other relevant parameters for image classification. Adam has been used as optimizer.

Development Pipeline: Python script has been used to get images from dataset, store in a buffer memory, make a shuffle of images categories to avoid memory of the sequence of defects.

Production Pipeline: edge server to prepare images and transmit to backend through API to reduce progressing latency









HORUS project - Identification of defects















NEXT STEPS

- Video acquisition and image extraction for spatial referencing and defects recognition.
 - ✓ Analysis on distorted/blurry photos has shown a good capability of defect detection
- Issuing of technical disposition and router card
 - ✓ *Training* on existing technical disposition on aeronautical parts (in-service defects)
 - ✓ Correlation between technical disposition and structured-text repair/rework/scrap route cards









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